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It consists of the mechanics of rigid bodies, mechanics of deformable bodies, and mechanics of fluids. The mechanics of rigid bodies is subdivided into statics and dynamics. Statics deals with bodies at rest; dynamics deals with bodies in motion. In this text, we assume bodies are perfectly rigid.

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Ferdinand P. Beer & E. Russell Johnston Jr. Vector Mechanics for Engineers ( Dynamics ) McGraw-Hill Book Company Inc. 1977 ( N.B.; book page numbering follows on from companion volume 'Statics' ) Acrobat 7 Pdf 127.0 Mb.

### **Vector Mechanics for Engineers ( Dynamics ) : Ferdinand P ...**

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Determine (a) the position, velocity and acceleration of A when  $t = 1$  s, (b) the maximum velocity and acceleration of A. SOLUTION  $x = 10\sin 2t + 15\cos 2t + 100$  dx  $v = 20 \cos 2t - 30\sin 2t$  dt dv  $a = -40\sin 2t - 60 \cos 2t$  dt For trigonometric functions set calculator to radians: (a)...

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